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Chuck is an active 25-year member of the IEEE Power System Relay Committee (PSRC) and is the past chairman of the Rotating Machinery Subcommittee. He is active in the IEEE IAS I&CPS, PCIC and PPIC committees, which address industrial system protection. He is a former U.S. representative to the CIGRE Study Committee 34 on System Protection and has chaired a CIGRE working group on generator protection. He also chaired the IEEE task force that produced the tutorial "The Protection of Synchronous Generators," which won the PSRC's 1997 Outstanding Working Group Award. Chuck is the 1993 recipient of the Power System Relay Committee's Career Service Award and he recently received the 2002 IAS I&CPS Ralph Lee Prize Paper Award. His papers have been republished in the IAS Industrial Applications Magazine.

Chuck has a Bachelor of Science in Electrical Engineering from Purdue University and is a graduate of the eight month GE Power System Engineering Course. He has authored a number of papers and magazine articles on protective relaying. He has over 25 years of experience as a protection engineer at Centerior Energy, a major investor-owned utility in Cleveland, Ohio where he was the Manager of the System Protection Section. He spent 10 years as the Applications Manager for Relay Products for Beckwith Electric. He is also a former instructor in the Graduate School of Electrical Engineering at Cleveland State University as well as a registered Professional Engineer in the state of Ohio and a Life Fellow of the IEEE.

## OUTLINE

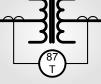
- IEEE PROTECTION STANDARDS
- WHY TRANSFORMERS FAIL
- TRANSFORMER BASICS
- PHASING STANDARDS
  - + IEEE/ANSI
  - + IEC
- TRANSFORMER DIFFERNTIAL
  - + Phase (87T)
  - + Gnd (87GD)
- OVEREXCITATION PROTECTION
- DIGITAL TRANSFORMER RELAYS

## **IEEE** Standards

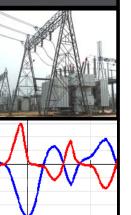
- Latest developments reflected in:
  - <u>Std. 242:</u> Buff Book Transformer Protection Chapter 11
  - ANSI / IEEEC37.91"Guide for Protective Relay Applications for Power Transformers"

*These are created/maintained by the IEEE PSRC & IAS They are updated every 5 years* 

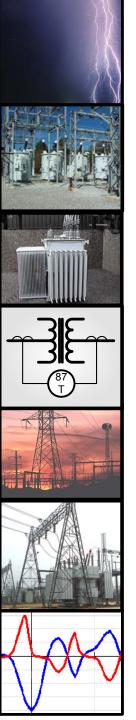








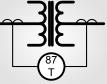
## WHY TRANSFORMERS FAIL



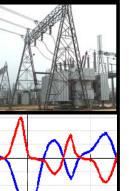
## What Fails in Transformers?

- Windings
  - Insulation deterioration from
    - Moisture
    - Overheating
    - Vibration
    - Voltage surges
    - Mechanical Stress from through-faults
- LTCs
  - Malfunction of mechanical switching mechanism
  - High resistance contacts
  - Overheating
  - Contamination of insulating oil





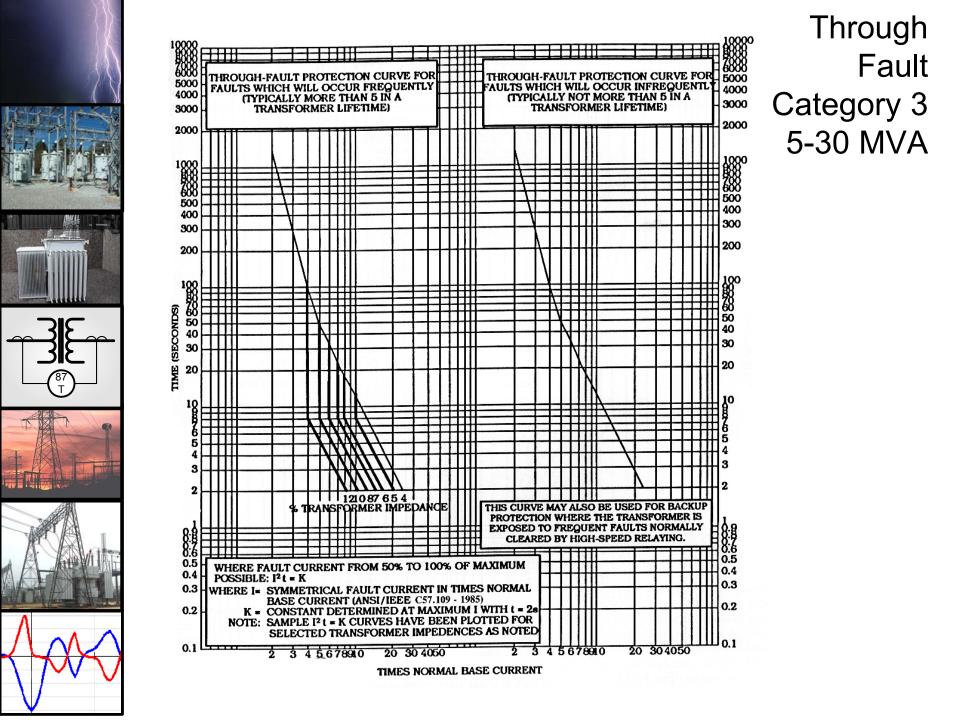


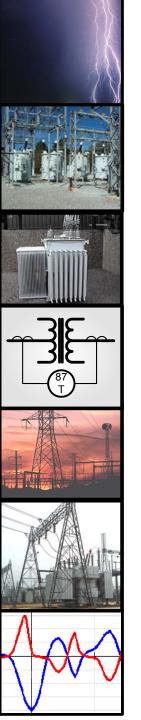


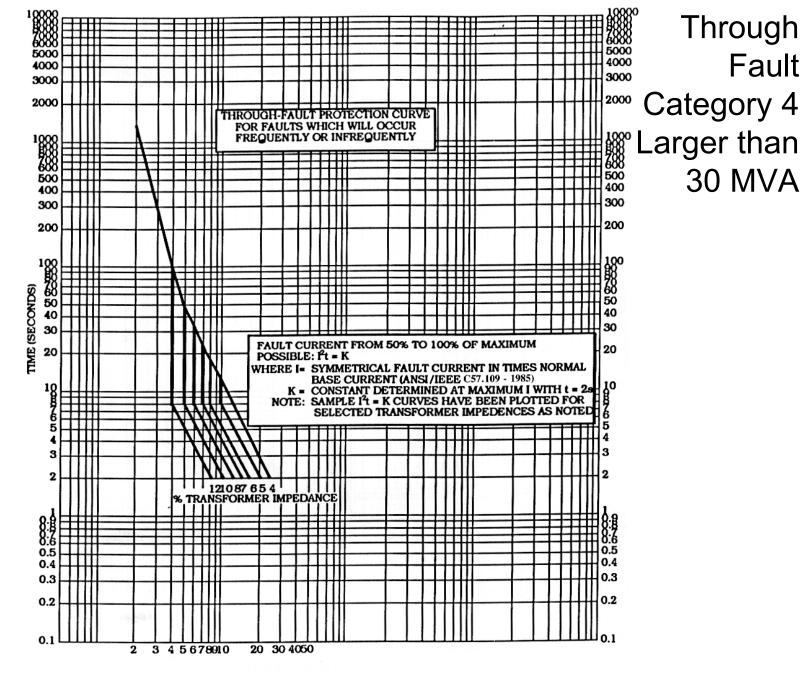
## What Fails in Transformers?

HARTFORD STEAM BOILER INSPECTION & INSURANCE CO.

Cause	% of Failures
Insulation Failure	26%
Manufacturing Problems	24%
Unknown	16%
Loose Connections	7%
Through Faults	5%
Improper Maintenance	5%
Oil Contamination	4%
Overloading	4%
Fire/Explosions	3%
Lighting	3%
Floods	2%
Moisture	1%





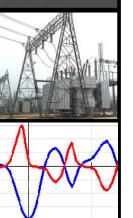


TIMES NORMAL BASE CURRENT

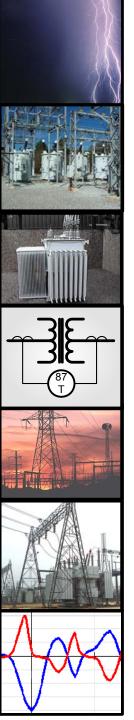








# TRANSFORMER PROTECTION BASICS

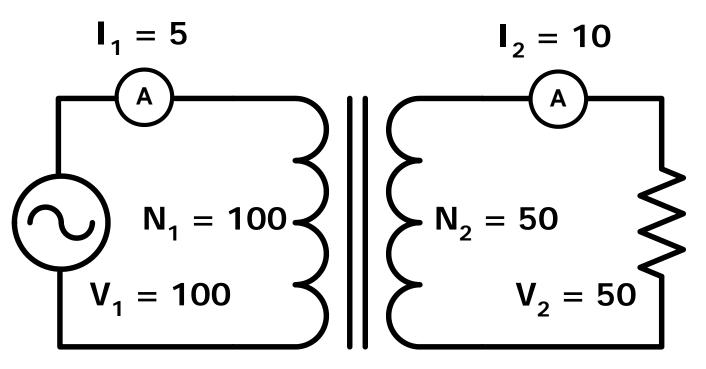


## **Transformer Formulas**

• 
$$\mathbf{V}_1 \mathbf{I}_1 = \mathbf{V}_2 \mathbf{I}_2$$

• 
$$\mathbf{N}_1 \mathbf{V}_2 = \mathbf{N}_2 \mathbf{V}_1$$

• 
$$N_1I_1 = N_2I_2$$



**Ideal Transformer – No Losses** 

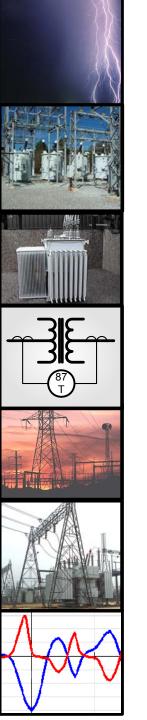
## **INSULATION MATERIALS**

### • <u>Dry</u>

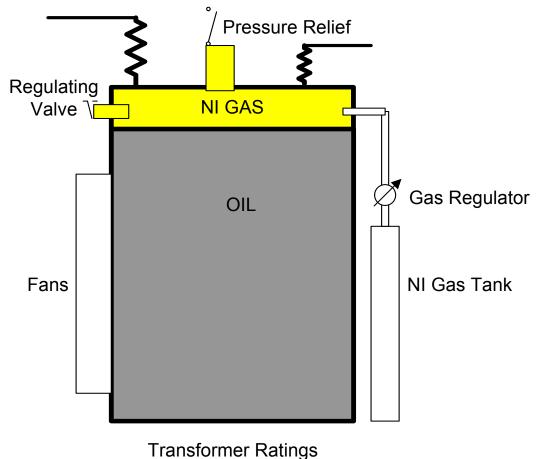
- Used where liquid spills cannot be tolerated
- Small ratings, lower voltage distribution

## • <u>Wet</u>

- Offers smaller size, lower cost and greater overload capacity
- Liquids have greater coefficient of heat transfer then dry insulation
- Vast majority of power transformers use wet (oil) insulation.

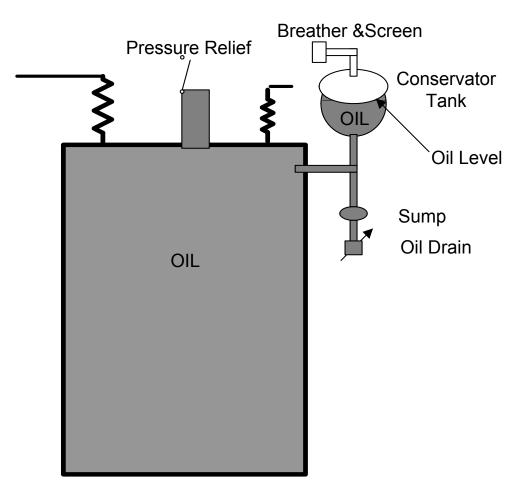


### Basic Transformer Designs Gas-Oil Sealed Transformers



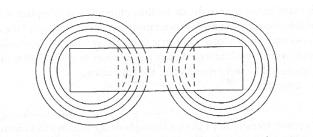
OA/FA/FA

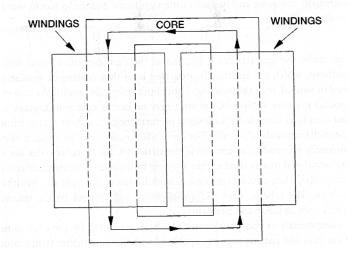
## Basic Transformer Designs Conservator Tank System



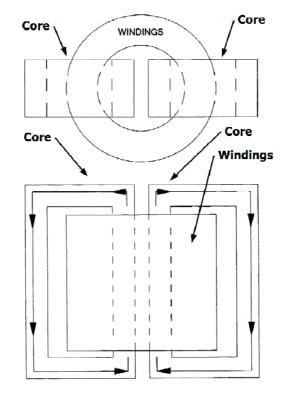
Transformer are Generally not Forced Cooled

### Basic Transformer Designs Shell & Core

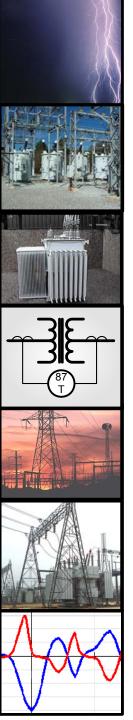




- Core Form
  - Single path for the magnetic circuit
  - Less \$\$\$



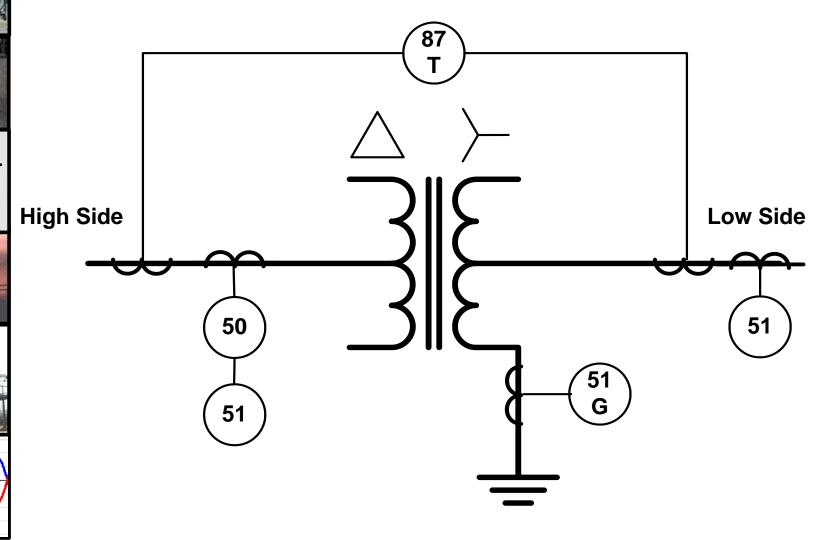
- Shell Form
  - Multiple paths for the magnetic circuit
  - Better through-fault withstand

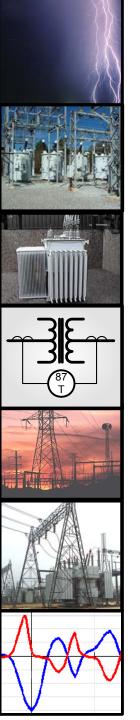


### IEEE Devices used in Transformer Protection

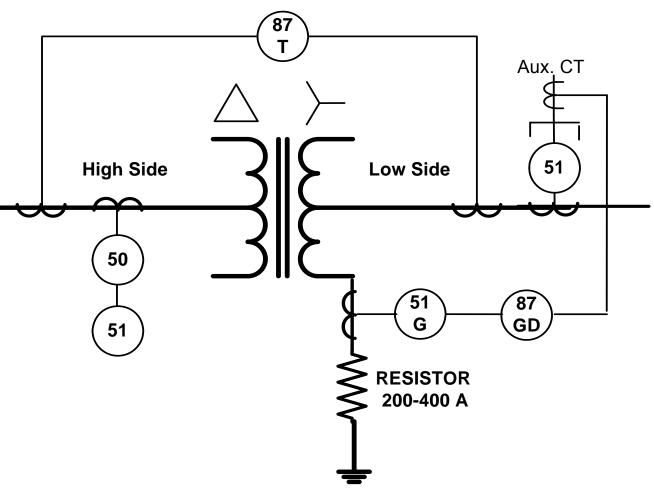
- 24: Overexcitation (V/Hz)
- 46: Negative Sequence Overcurrent
- 49: Thermal Overload
- 50: Instantaneous Phase Overcurrent
- 50G: Instantaneous Ground Overcurrent
- 50N: Instantaneous Neutral Overcurrent
- 50BF: Breaker Failure
- 51G: Ground Inverse Time Overcurrent
- 51N: Neutral Inverse Time Overcurrent
- 63: Sudden Pressure Relay (Buccholtz Relay)
- 81U: Underfrequency
- 87HS: High-set Phase Differential (Unrestrained)
- 87T: Transformer Phase Differential with Restraints
- **87GD**: Ground Differential (also known as "restricted earth fault")

## BASIC UTILITY SOLIDLY GROUNDED TRANSFORMER PROTECTIONS





### Basic Industrial Transformer Protection

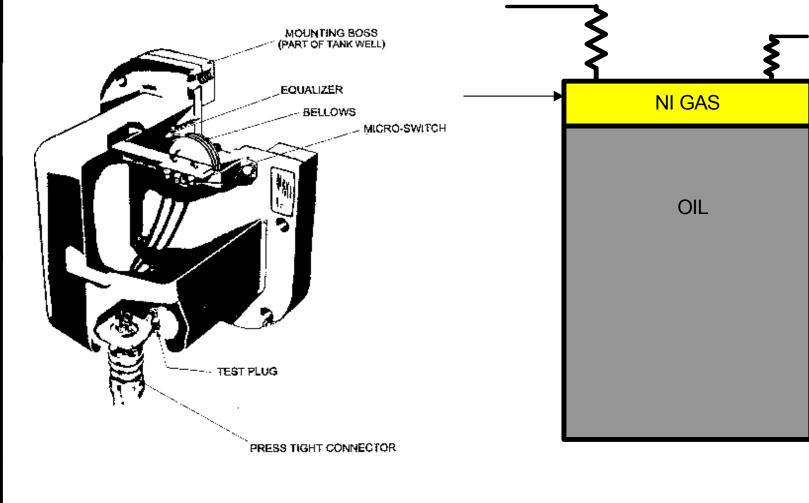


## **Types of Protection**

#### **Mechanical**

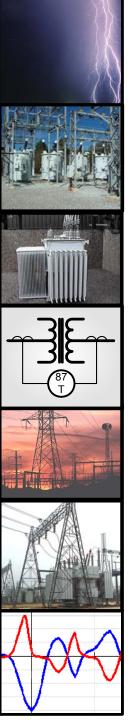
- Accumulated Gases
  - Arcing by-products
- Pressure Relays
  - Arcing causing pressure waves in oil or gas space
- Thermal
  - Caused by overload, overexcitation, harmonics and geo magnetically induced currents
    - Hot spot temperature
    - Top Oil
    - LTC Overheating

### Sudden Pressure Relay (SPR) Protection

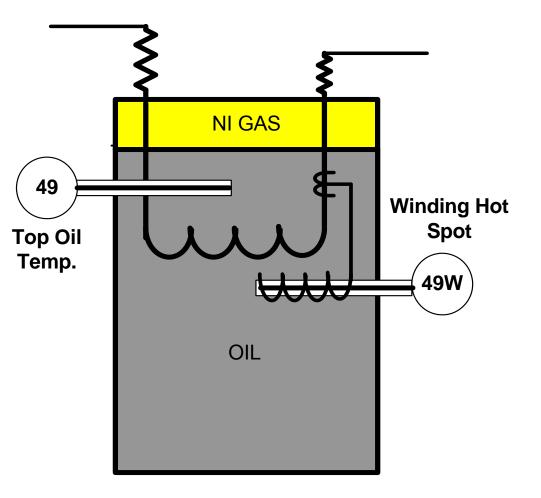


Sudden Pressure Relay

Transformer



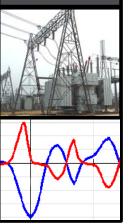
### **Transformer Thermal Monitoring**











## **Types of Protection**

#### <u>Fuses</u>

Small transformers ( <10 MVA Solidly Grounded) Short circuit protection only

#### **Overcurrent Protection**

High side

Through fault protection

Differential back-up protection for high side faults

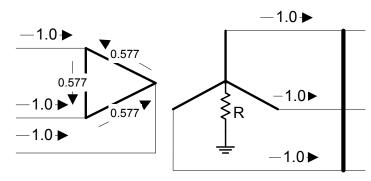
Low side

System back up protection

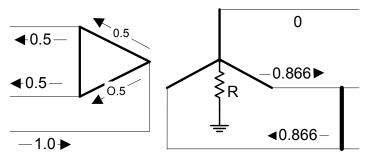
#### **Differential Protection**

Phase Diff. Ground Diff.

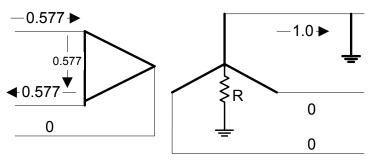
### DELTA-WYE TRANSFORMERS UNDER FAULT CONDITIONS



A) Three Phase Fault

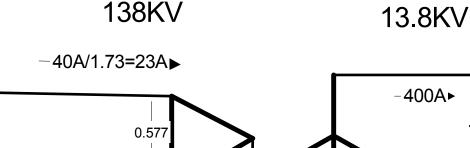


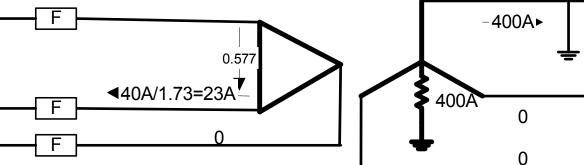
B) Phase to Phase Fault in pu of Three Phase Fault



C) Line to Ground Fault

### DELTA-WYE TRANSFORMERS LIMITATIONS OF FUSING



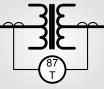


Line to Ground Fault 10 MVA 138/13.8KV

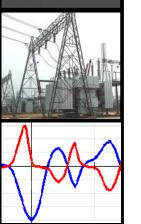
I<sub>FI</sub> = 10,000/1.73 X 138 = 42A

#### WHEN FUSES ARE SIZED TO CARRY LOAD THEY CAN'T DETECT A GROUND FAULT

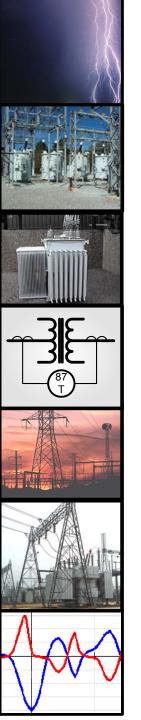








# TRANSFORMER PHASING STANDARDS IEEE/ANSI & IEC



## ANSI/IEEE PHASING STANDARD

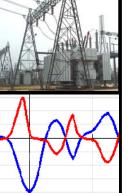
- H1, H2, H3
  - Primary Bushings

- X1, X2, X3
  - Secondary Bushings



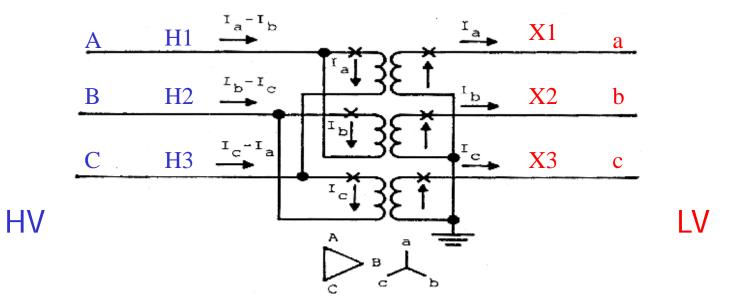
Wye-Wye Delta-Delta Delta-Wye Wye-Delta H1 and X1 at zero degreesH1 and X1 at zero degreesH1 lead X1 by 30 degreesH1 lead X1 by 30 degrees





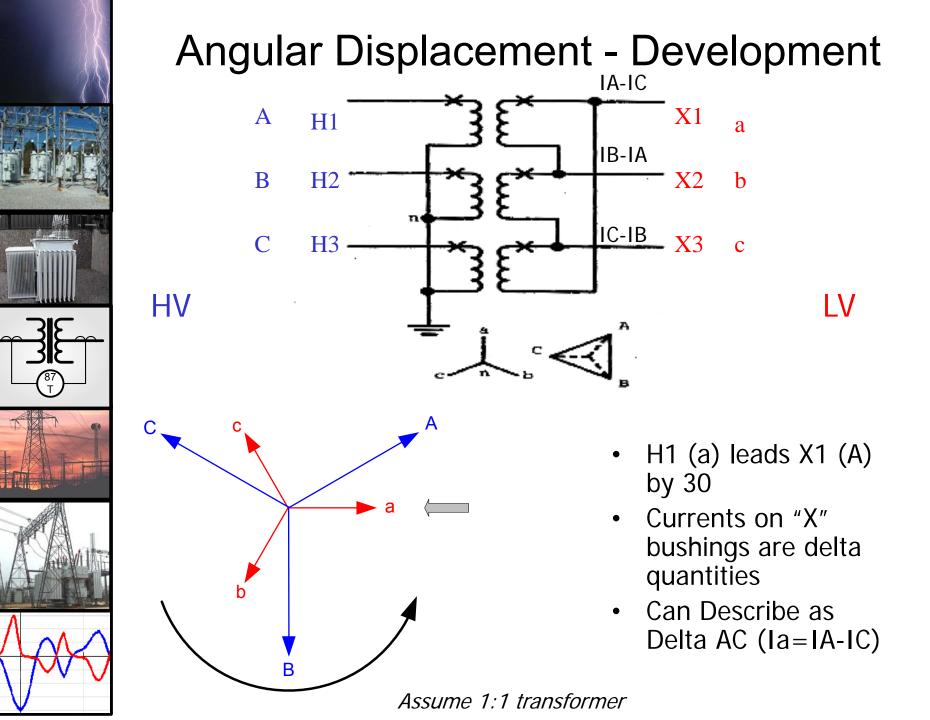
b

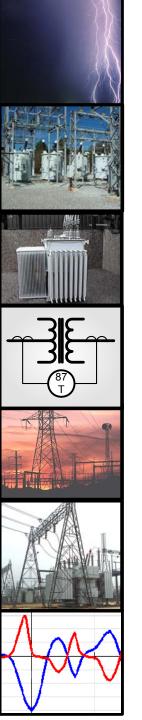
### Angular Displacement - Development



- H1 (A) leads X1 (a) by 30
  - Currents on "H" bushings are delta quantities
  - Can Describe as Delta AB (Ia = Ia-Ib)

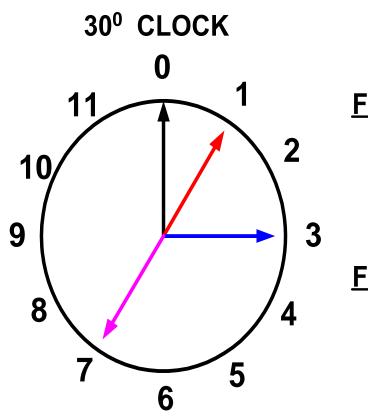
Assume 1:1 transformer





### Transformer Phasing – IEC Phasing Standard Euro-designations use 30° increments of LAG

from the X1 bushing to the H1 bushings



#### **EXAMPLES**

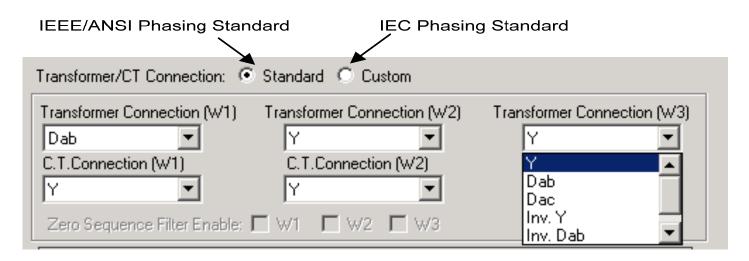
For Delta Primary Transformers:  $1 = Dy1 = X \text{ lags H by } 30^{0}$   $3 = Dy3 = X \text{ lags H by } 90^{0}$  $7 = Dy7 = X \text{ lags H by } 210^{0}$ 

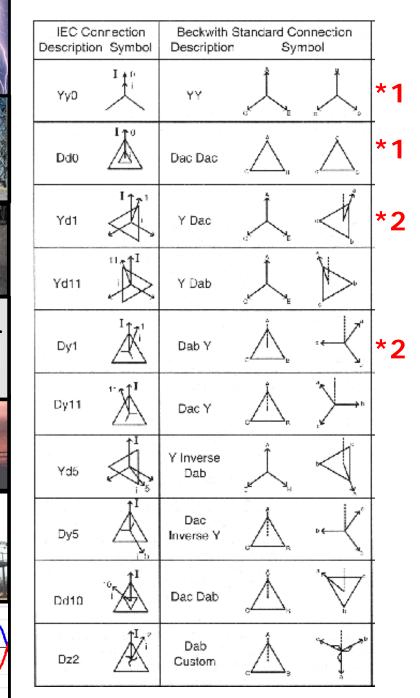
#### For Wye Primary Transformers:

- $1 = Yd1 = X lags H by 30^{0}$
- $3 = Yd3 = X lags H by 90^{0}$
- $7 = Yd7 = X \text{ lags H by } 210^{\circ}$

## Transformer Phasing Communicating Phasing To Digital Relays

- Major Source of Setting Error
- IEEE-ANSI Can use  $\Delta$  AB or  $\Delta$  AC
- IEC Need to Use 30° Clock
- CT's Can be Δ or Y
- Solution: Let the Software Decide



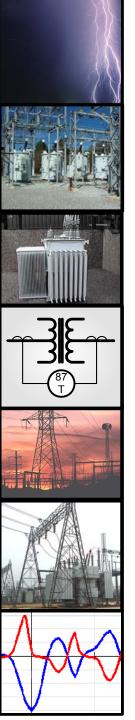


## Angular Displacement

- IEC (Euro) practice does not have a standard like ANSI
  - Most common connection is Dy11 (low lead high by 30!)
- Obviously observation of angular displacement is extremely important when paralleling transformers!

\*1 = ANSI std. @  $0^{\circ}$ 

\*2 = ANSI std. @ X1 lag H1 by 30°, or "high lead low by 30  $^\circ$  "

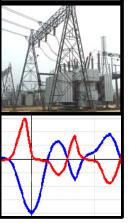


## Winding Arrangements

- Wye-Wye
  - Conduct zero-sequence between circuits
  - Provides ground source for secondary circuit
- Delta-Delta
  - Blocks zero-sequence between circuits
  - Does not provide a ground source
- Delta-Wye
  - Blocks zero-sequence between circuits
  - Provides ground source for secondary circuit
- Wye-Delta
  - Blocks zero-sequence between circuits
  - Does not provide a ground source for secondary circuit







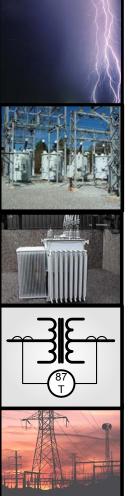
# TRANSFORMER DIFFERENTIAL PROTECTION

## **Types of Protection**

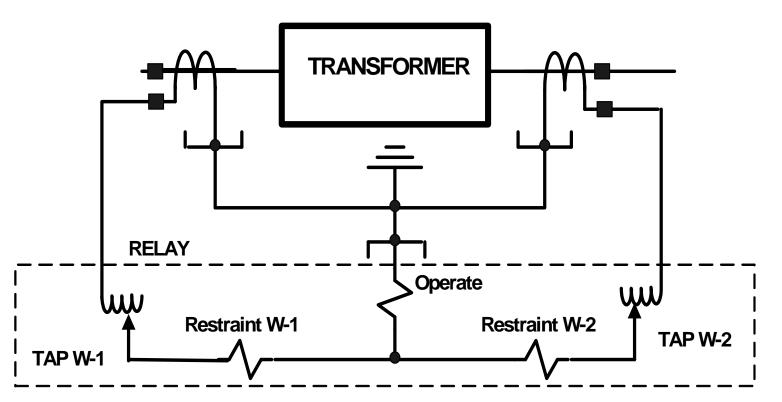
### **Electrical**

### Phase Differential

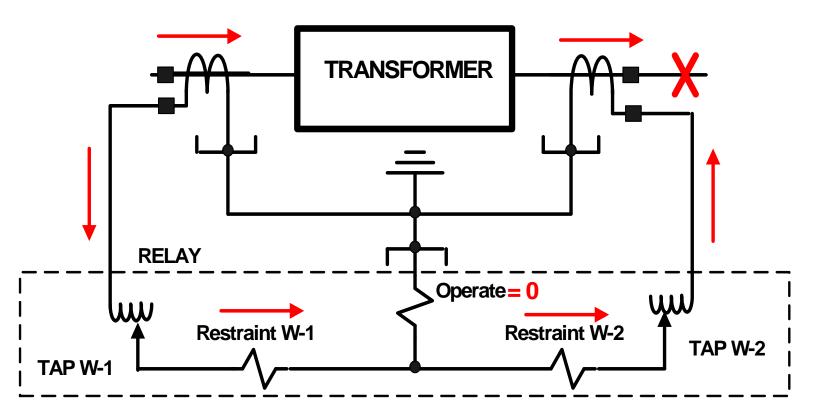
- Applied with variable percentage slopes to accommodate CT saturation and CT ratio errors
- Applied with inrush and overexcitation restraints
- Set with at least a 15% pick up to accommodate CT performance
  - Class "C" CT; 10% at 20X rated
- If unit is LTC, add another 10%
- May not be sensitive enough for all faults (low level, ground faults near neutral, resistor grounded transformers )



## **Basic Differential Relay**

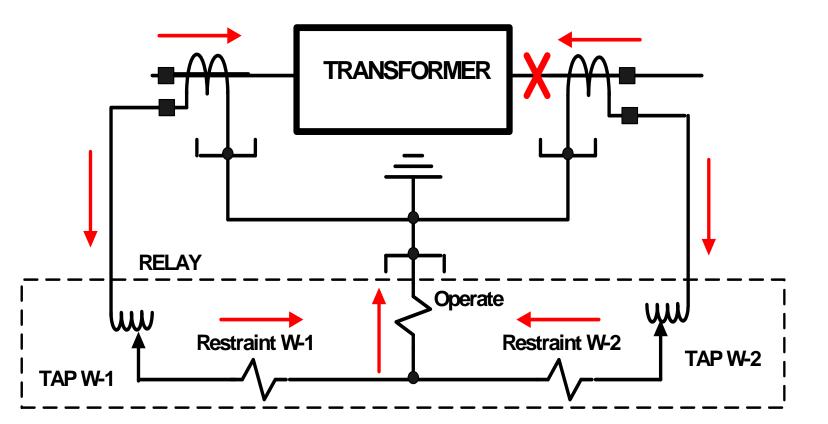


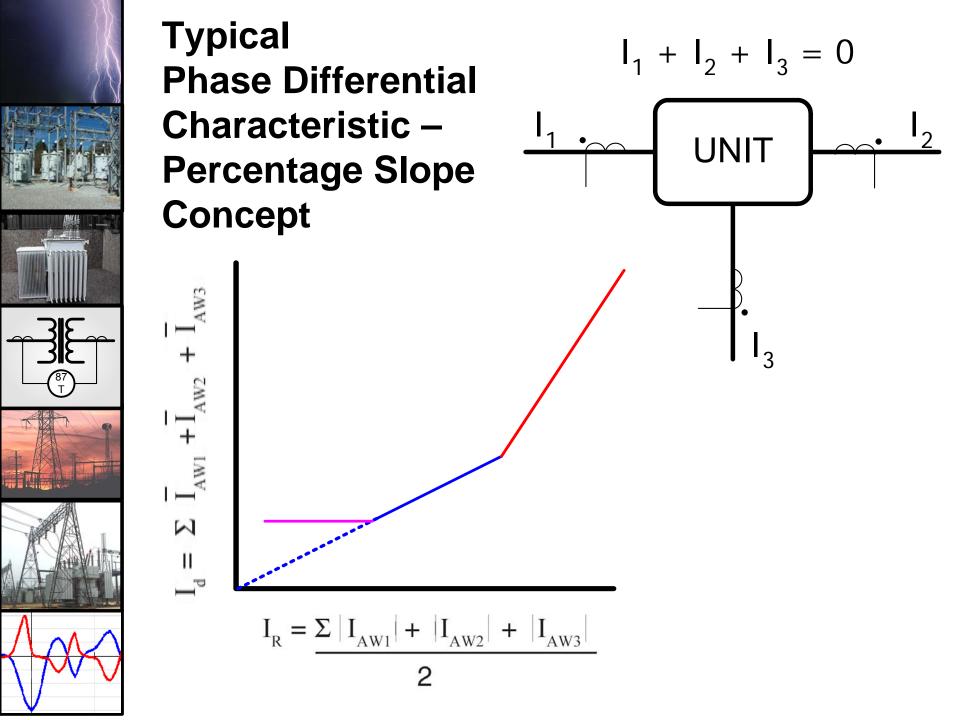
## Basic Differential Relay External Fault



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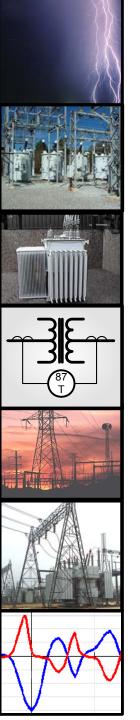
## Basic Differential Relay Internal Fault





### Unique Issues Applying to Transformer Differential Protection

- CT ratio caused current mismatch
- Transformation ratio caused current mismatch (fixed taps)
- LTC induced current mismatch
- Delta-wye transformation of currents
  - Vector group and current derivation issues
- Zero-sequence current elimination for external ground faults on wye windings
- Inrush phenomena and its resultant current mismatch



#### **Classical Differential Compensation**

- CT ratios must be selected to account for:
  - Transformer ratios
  - If delta or wye connected CTs are applied
  - Delta increases ratio by 1.73
- Delta CTs must be used to filter zerosequence current on wye transformer windings

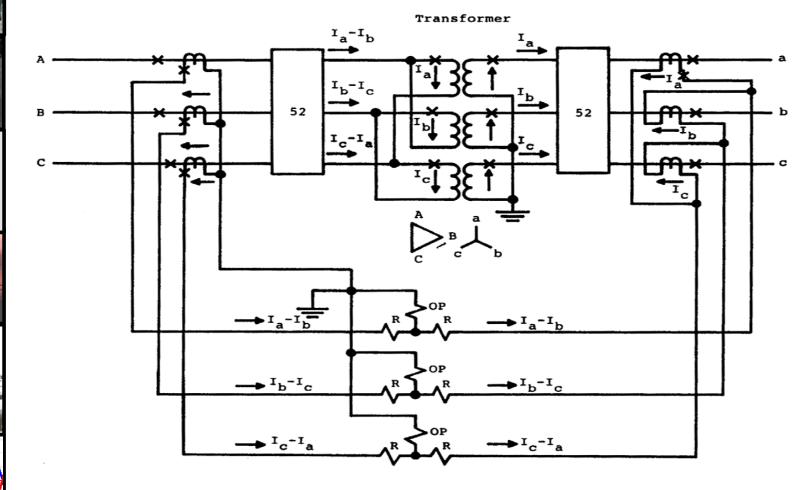
### Unique Issues Applying to Transformer Differential Protection

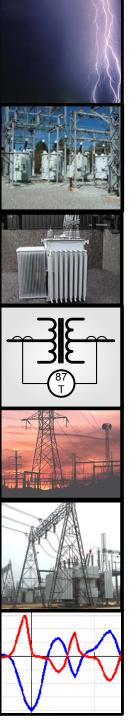
- Harmonic content availability during inrush period due to point-on-wave switching (especially with newer transformers)
- Overexcitation phenomena and its resultant current mismatch
- Internal ground fault sensitivity concerns
- Switch onto fault concerns
- CT saturation, remnance and tolerance

#### Classical Electro-Mechanical Differential Compensation

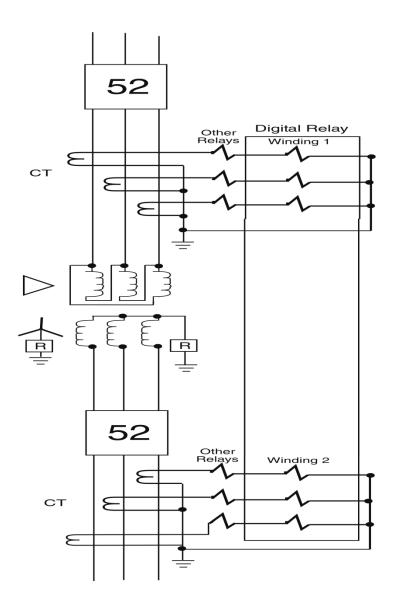
PRI. (H)

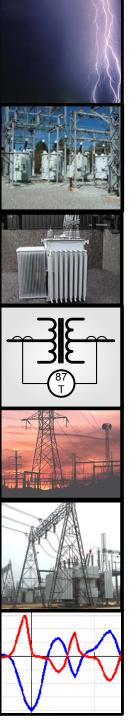
SEC. (X)





## **Digital Relay Application**

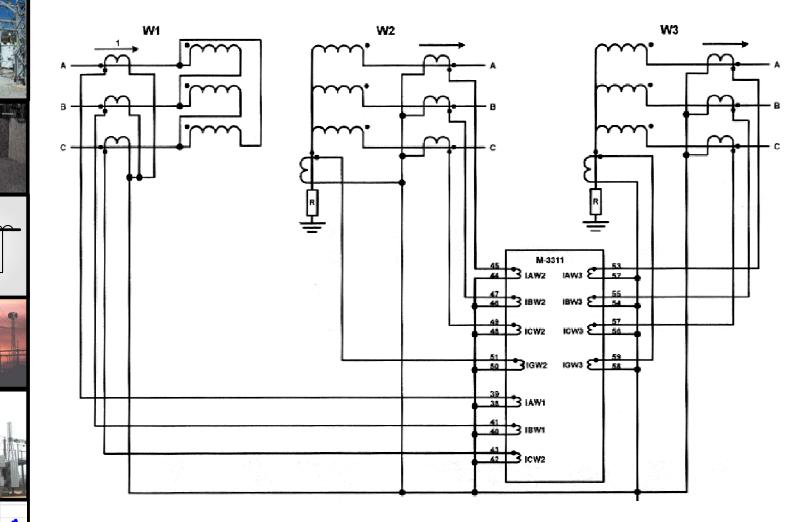




## **Compensation in Digital Relays**

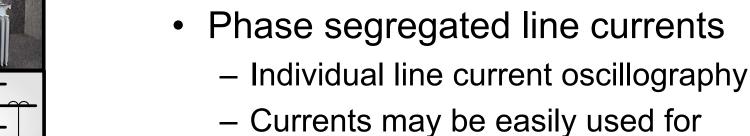
- Transformer ratio
- CT ratio
- Vector quantities
  - Which vectors are used
  - Where the 1.73 factor ( $\sqrt{3}$ ) is applied
    - When examining line to line quantities on delta connected transformer windings and CT windings
- Zero-sequence current filtering for wye windings so the differential quantities do not occur from external ground faults

# **Digital Relay Application**



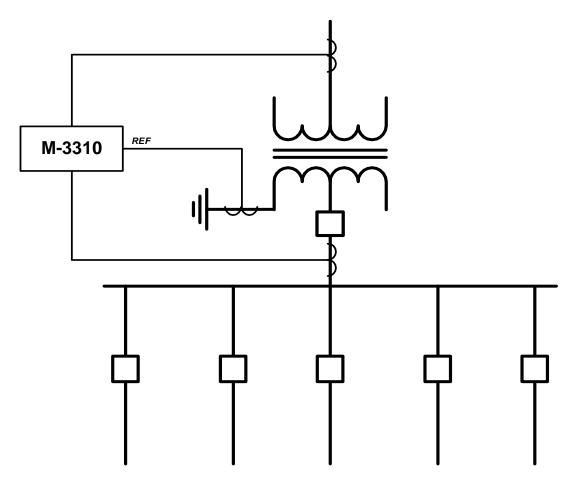
All wye CTs shown, can retrofit legacy delta CT applications

# Benefits of Wye CTs



- Currents may be easily used for overcurrent protection and metering
- Easier to commission and troubleshoot
- Zero sequence elimination performed by calculation
- BUT IS IT WORTH ALL THE RE-WIRING IN RETRO-FIT APPICATIONS ?

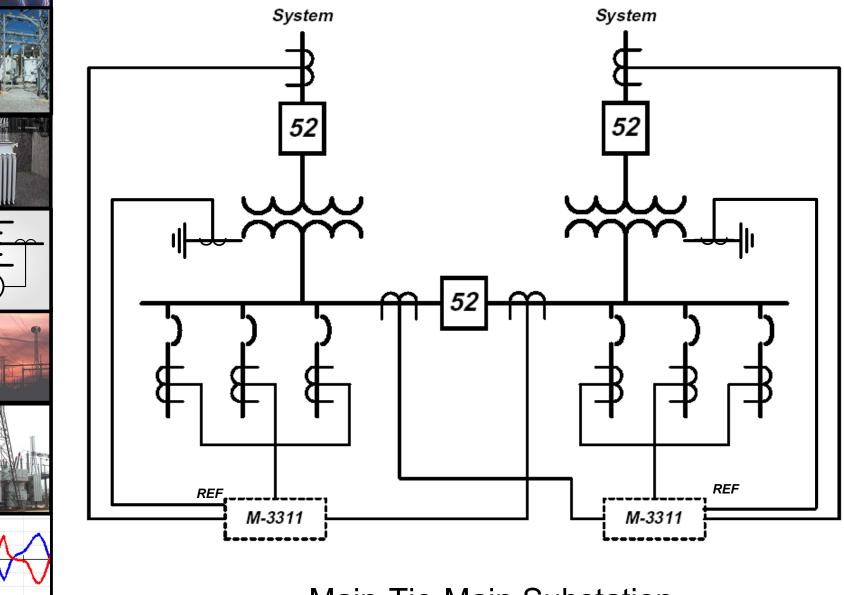
#### **Typical Applications**



Two winding transformer, with Neutral Input

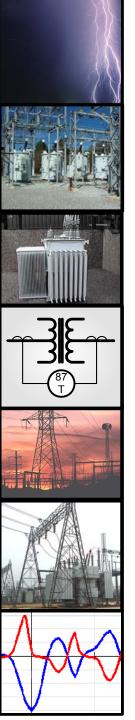


#### **Typical Applications**



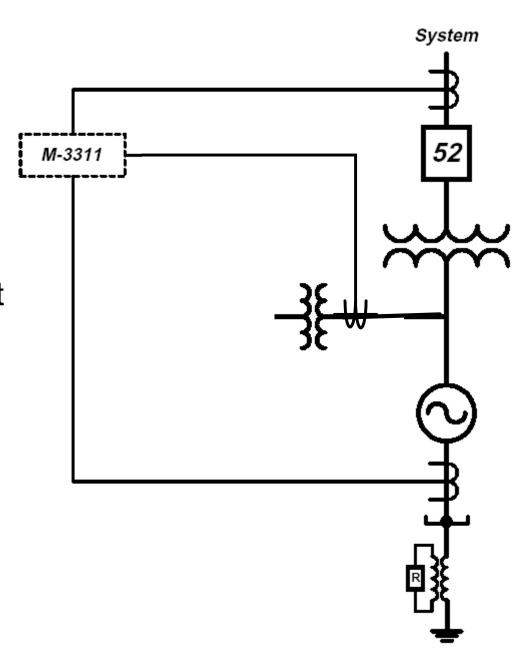
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Main-Tie-Main Substation

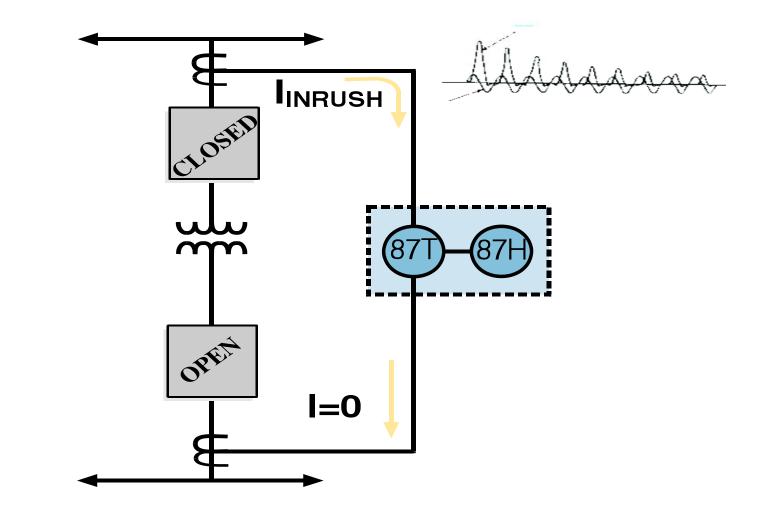


#### Typical Applications

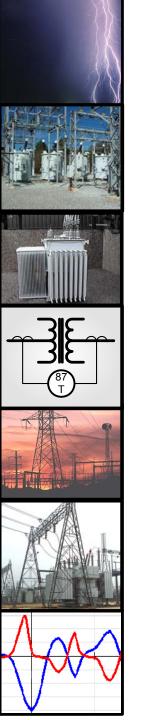
 Generator unit differential wrap



#### **Inrush Restraint**

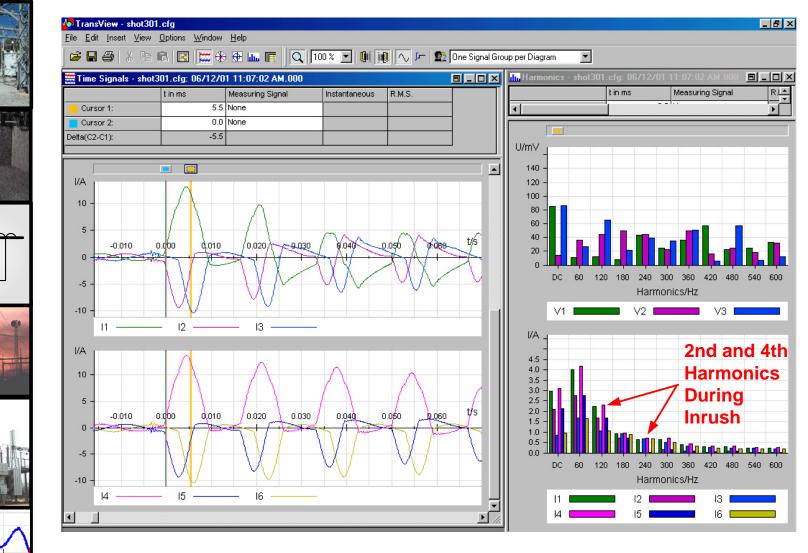


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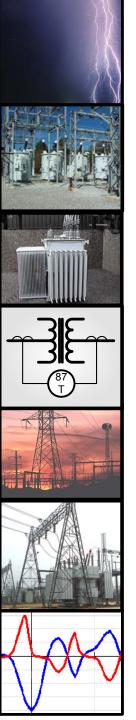


- Inrush Detection and Restraint
  - 2<sup>nd</sup> harmonic restraint has been employed for years
  - "Gap" detection has also been employed
  - As transformers are designed to closer tolerances, both 2<sup>nd</sup> harmonic and low current gaps in waveform have decreased
  - If 2<sup>nd</sup> harmonic restraint level is set too low, differential element may be blocked for internal faults with CT saturation (with associated harmonics generated)

- Inrush Detection and Restraint
  - 4<sup>th</sup> harmonic is also generated during inrush
  - Odd harmonics are not as prevalent as Even harmonics during inrush
  - Odd harmonics more prevalent during CT saturation
  - Use 4<sup>th</sup> harmonic and 2<sup>nd</sup> harmonic together
  - M-3310/M-3311 relays use RMS sum of the 2<sup>nd</sup> and 4<sup>th</sup> harmonic as inrush restraint
  - Result: Improved security while not sacrificing reliability

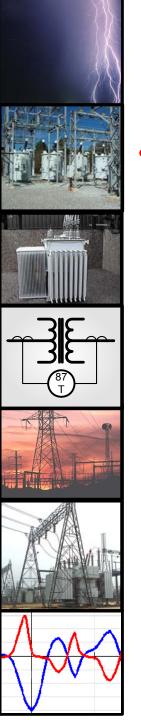


Typical Transformer Inrush Waveform

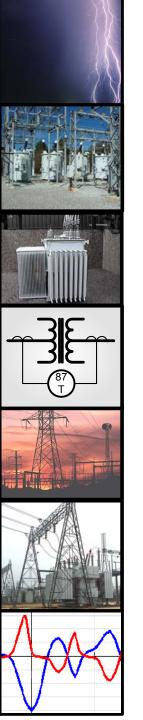


# Cross Phase Averaging $I_{dc_{PA24}} = \sqrt{I A_{d24}^2 + I B_{d24}^2 + I C_{d24}^2}$

- Provides security if any phase has low harmonic content during inrush or overexcitation
- This can occur depending on the voltage point-on-wave when the transformer is energized for a given phase
- Cross phase averaging uses the average of harmonics on all three phases to determine level

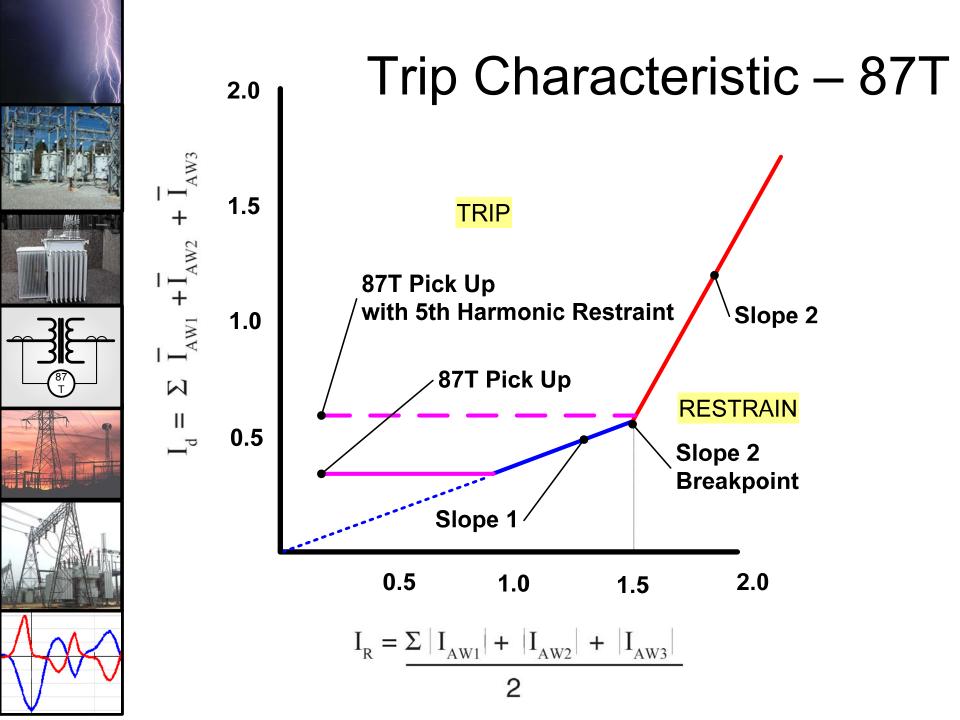


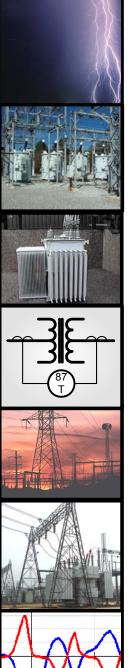
- **Overexcitation Restraint** 
  - Overexcitation occurs when volts per hertz level rises (V/Hz)
  - This typically occurs from load rejection and malfunctioning generation AVRs
  - The voltage rise at nominal frequency causes the V/Hz to rise
  - This causes 5<sup>th</sup> harmonics to be generated in the transformer as it begins to go into saturation
  - The current entering the transformer is more than the current leaving due to this increase in magnetizing current
  - This causes the differential element to pick-up
  - Use 5<sup>th</sup> harmonic level to detect overexcitation



#### Overexcitation Restraint

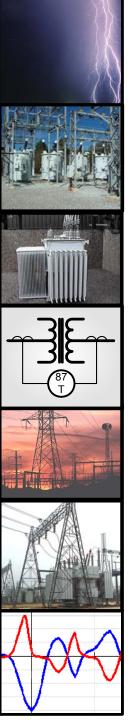
- Most other relays block the differential element from functioning during transformer overexcitation
- M-3310/M-3311 do not block it, but rather raise the pick up level to accommodate the difference currents caused by the transformer saturation
- This allows the differential element to trip if an internal fault occurs during the overexcitation period due to increased stress level on the insulation
- Result: Improved reliability while not sacrificing security





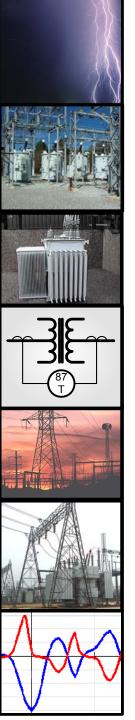
# Trip Characteristic – 87T

- 87T Pick Up
  - Class C CTs, use 10%
  - 5% Margin
  - LTC, add 10%
  - Magnetizing losses, add 1%
  - 0.15 to 0.3 pu typically setting
- Slope 1
  - Used for low level currents
  - Can be set as low as 15%
  - With LTC 25-30%
- Slope 2 "breakpoint"
  - Typically set at 2X rated current
  - This setting assumes that any current over 2X rated is a through fault or internal fault, and is used to desensitize the element against unfaithful replication



# Trip Characteristic – 87T

- Slope 2
  - Typically set at 60% (double slope 1)
- Inrush Restraint (2<sup>nd</sup> and 4<sup>th</sup> harmonic)
  - Typically set from 10-15%
  - Employ cross phase averaging blocking for security– Blocks tripping for 10 cycles
- Overexcitation Restraint (5<sup>th</sup> harmonic)
  - Typically set at 30%
  - Raise 87T pick up by 200% or 0.60 pu during overexcitation
  - No cross phase averaging needed, as overexcitation is symmetric on the phases

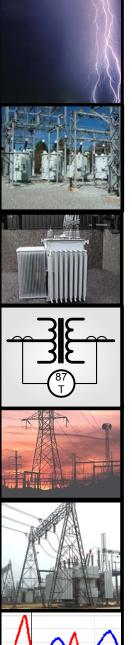


# Trip Characteristic – 87H

- 87H Pick Up
  - Typically set at 10pu rated current
  - This value should be above maximum possible inrush current and lower than the CT saturation current
  - C37.91, section 5.2.3, states 10pu an acceptable value
  - Can use data captured from energizations to fine tune the setting

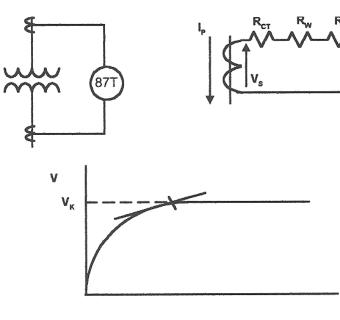
## **CT** Issues

- <u>Remnance</u>: Residual magnetism that causes dc saturation of the CTs
- <u>Saturation</u>: Error signal resulting from too high a primary current combined with a large burden
- <u>Tolerance</u>: Class "C" CTs are rated 10% for currents x20 of nominal
  - Thru-faults and internal faults may reach those levels depending on ratio selected



#### **IS THE CT GOOD ENOUGH ?**

- Provides security for high fault current levels outside the differential zone where CT inputs can saturate.
- Factors effecting CT saturation
  - Residual magnetism in CT core
  - CT characteristic mismatch
  - CT circuit burden
- <u>CT Burden Check</u>– want to operate below the knee-point voltage  $(V_k)$  for worst-case fault external to diff. Zone.



$$V_{\rm S} = \frac{I_{\rm P}}{\rm N} \left[ R_{\rm CT} + R_{\rm W} + R_{\rm R} \right]$$

Where I<sub>P</sub> is the maximum external fault current

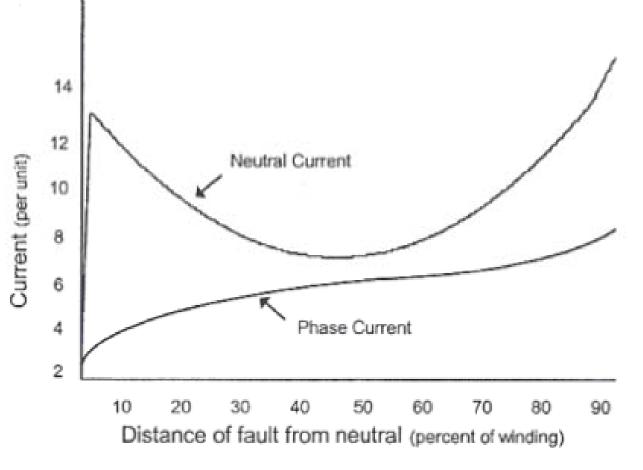
## **CT** Issues

- Best defense is to use high "Class C" voltage levels
  - C200,C400, C800
  - These have superior characteristics against saturation and relay/wiring burden
- Use low burden relays
  - Digital systems are typically 0.020 ohms
- Use a variable percentage slope characteristic to desensitize the differential element when challenged by high currents that may cause replication errors

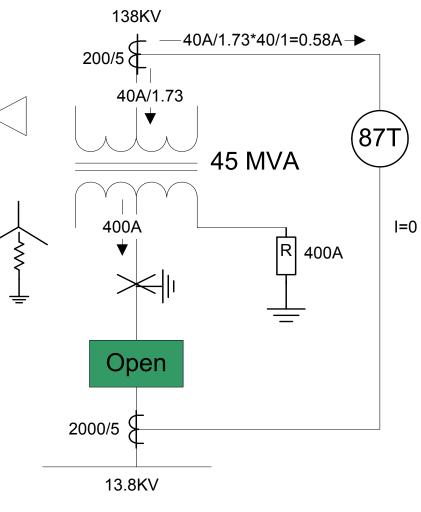
#### Improved Ground Fault Sensitivity Ground Differential Protection (87GD)

- 87T element is typically set with 15-30% pick up -
- This is to accommodate Class "C" CT accuracy during a fault plus the effects of LTCs
- That leaves 10-15% of the winding not covered for a ground fault (Solidly Grounded Winding)
- When a neutral resistor limits ground current to 200-400A <u>no</u> ground fault protection is provided for that winding by the 87T element.
- Employ a ground differential element to improve sensitivity (87GD)

# Differential Sensitivity Reduced for Ground Fault Near the Neutral



### Improved Ground Fault Sensitivity



Typical Pickup of 87T:

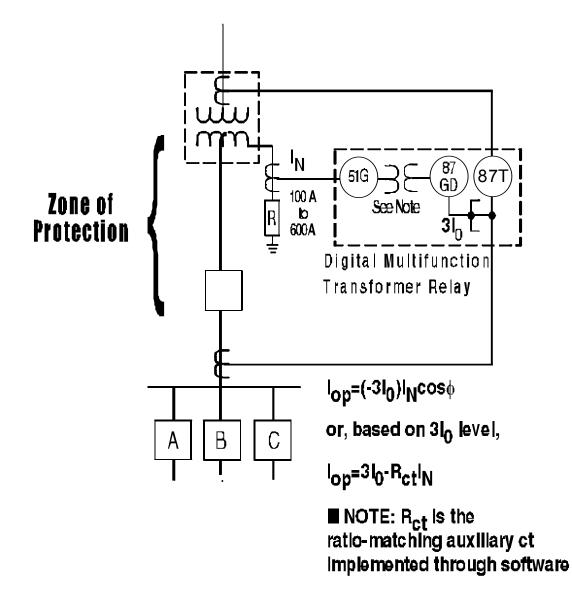
- O.3 pu pickup
- Relay Tap set at Trans. Rating (45MVA)

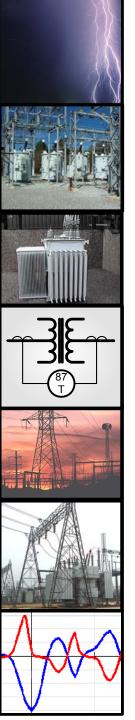
I<sub>FL138KV</sub> = 4.71 Amps

• PU = 4.71A x 0.3 = 1.41A

 WITHOUT GROUND DIFF. (87GD) THERE IS <u>NO</u> HIGHSPEED PROTECTION FOR SEC. GND FAULTS

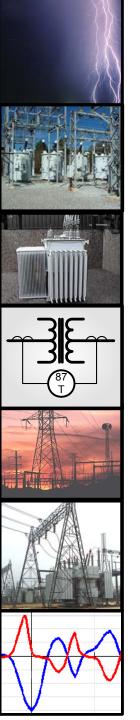
#### Improved Ground Fault Sensitivity



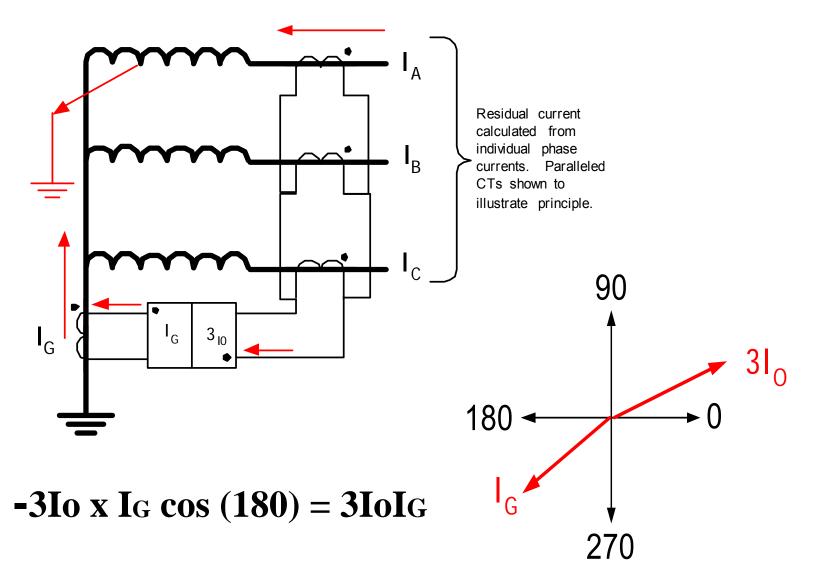


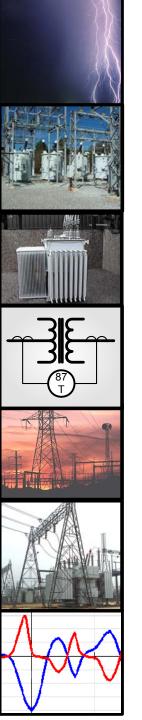
# Trip Characteristic – 87GD

- 87GD Pick Up
  - Element normally uses directional comparison between phase residual current (3I<sub>0</sub>) and measured ground current (I<sub>G</sub>)
    - No user setting
  - Pick up only applicable when 3I<sub>0</sub> current is below 140mA (5A nom.)
    - Pick up =  $3I_0 I_G$
  - If  $3I_0$  greater than 140mA, element uses:
    - $-3I_0 * I_G * \cos\theta$ . It will trip only when the directions of the currents is opposite, indicating an internal fault
    - Using direction comparison mitigates the effects of saturation on the phase and ground CTs

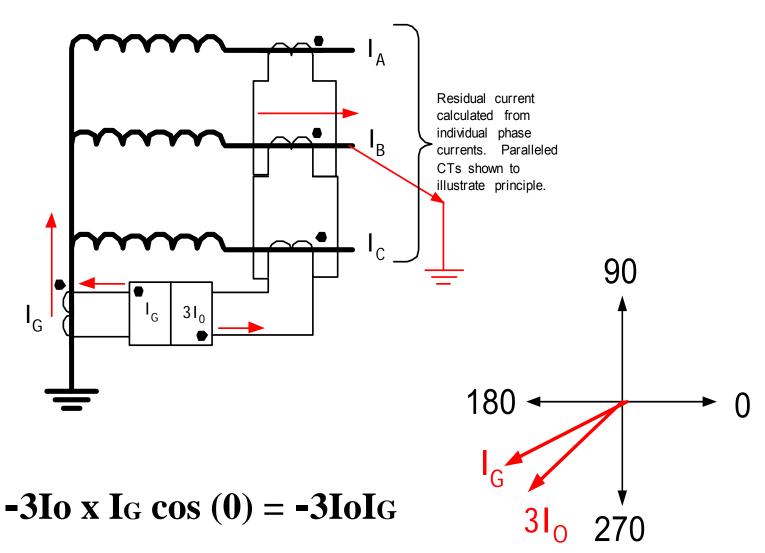


## Trip Characteristic – 87GD

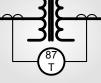




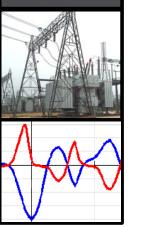
## Trip Characteristic – 87GD









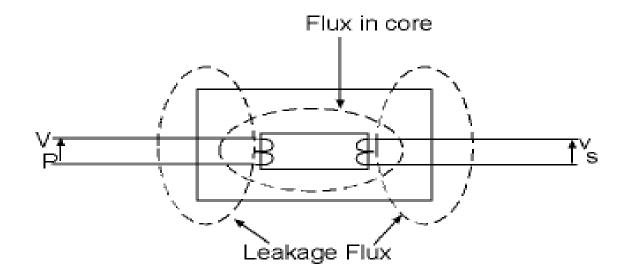


# TRANSFORMER OVEREXCITATION PROTECTION

# **Transformer Limits**

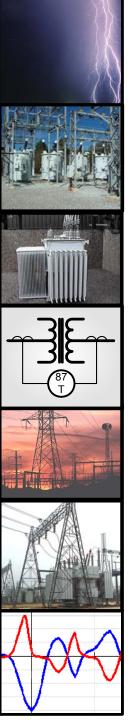
- Overexcitation
  - Responds to overfluxing; excessive V/Hz
  - Continuous operational limits
    - ANSI C37.91 & C57.12
      - 1.05 loaded, 1.10 unloaded
      - Measured at the transformer output
    - Inverse curves typically available for values over the continuous allowable maximum
    - Protection required application of V/Hz (24) protection

# Overexcitation/ Volts per Hertz (24)

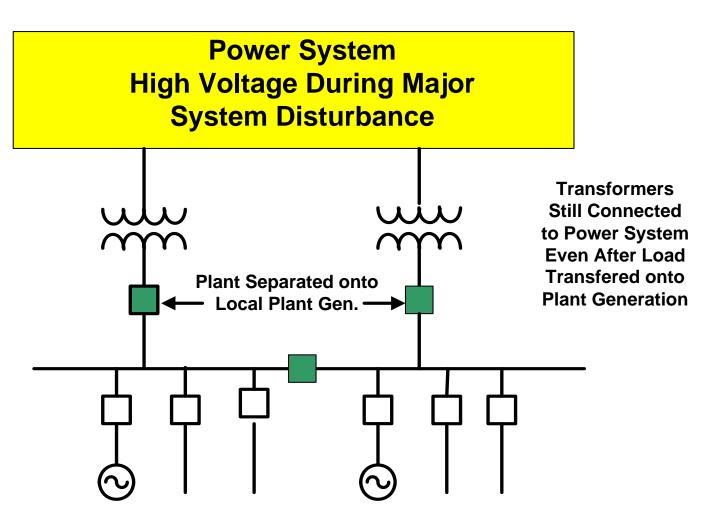


### PHYSICAL INSIGHTS

- As voltage rises above rating leakage flux increases
- Leakage flux induces current in transformer support structure causing rapid localized heating



### Industrial System Overexcitation



### Overexcitation Event on EHV Transmission System

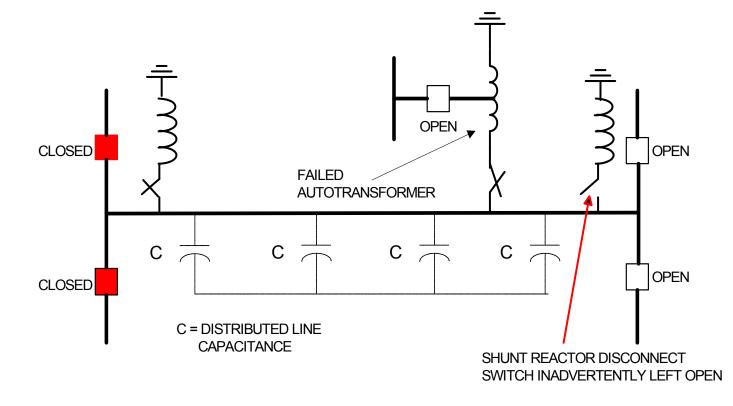
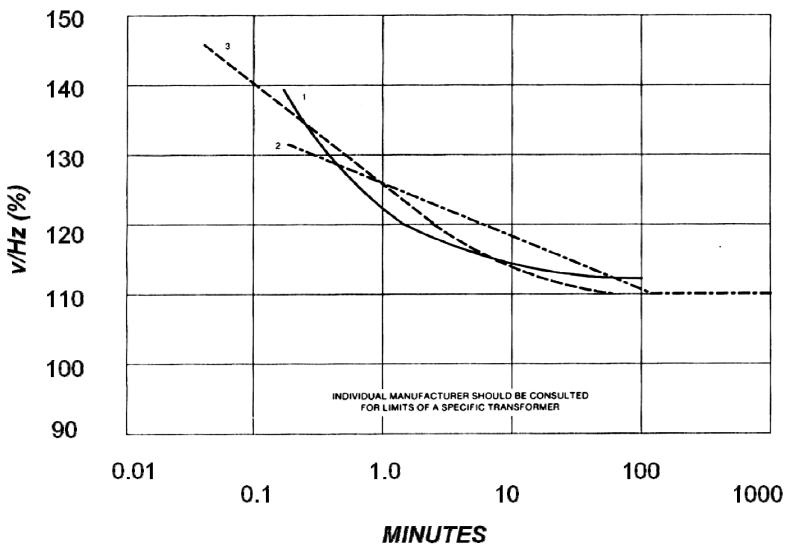
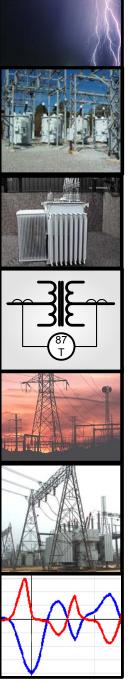


Fig. 11 Overexcitation Failure of an EHV Autotransformer

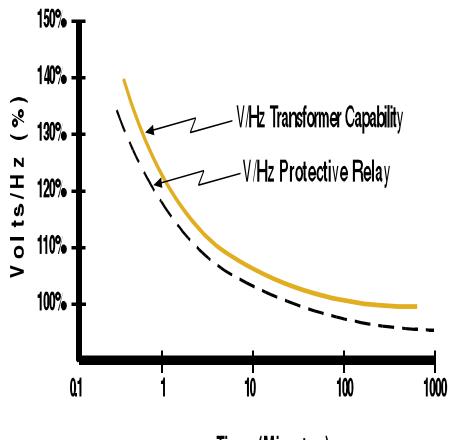
### **Overexcitation Curve**



This is typically how the apparatus manufacturer specs it

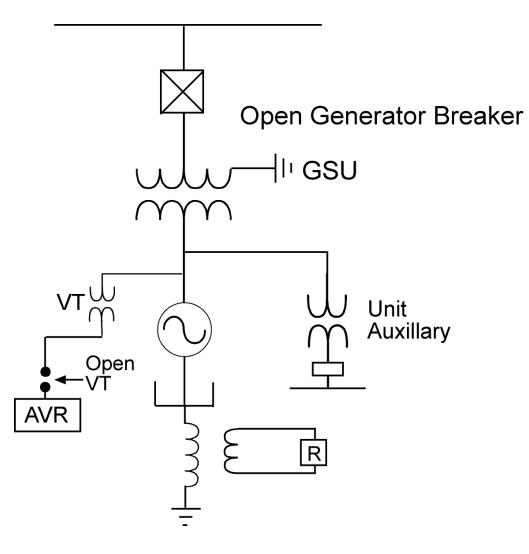


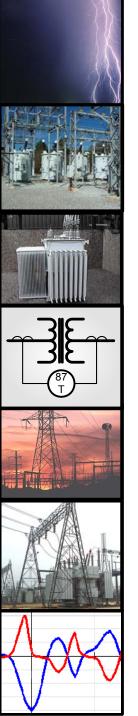
## **Overexcitation Digital Relay Curve**



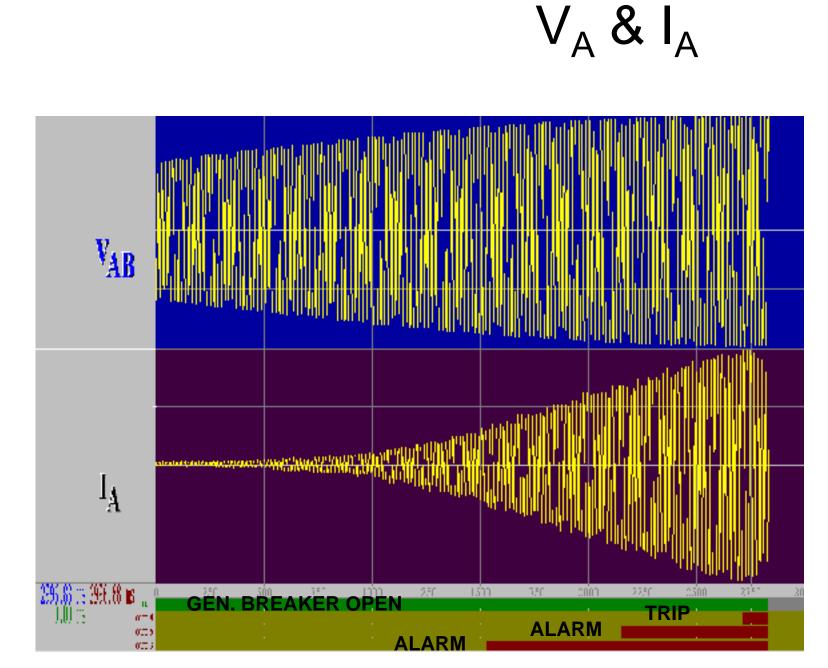
Time (Minutes)

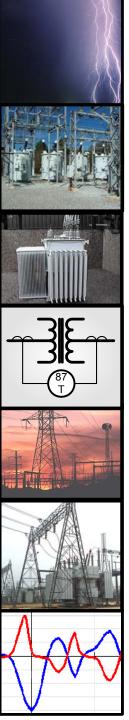
# V/Hz Event

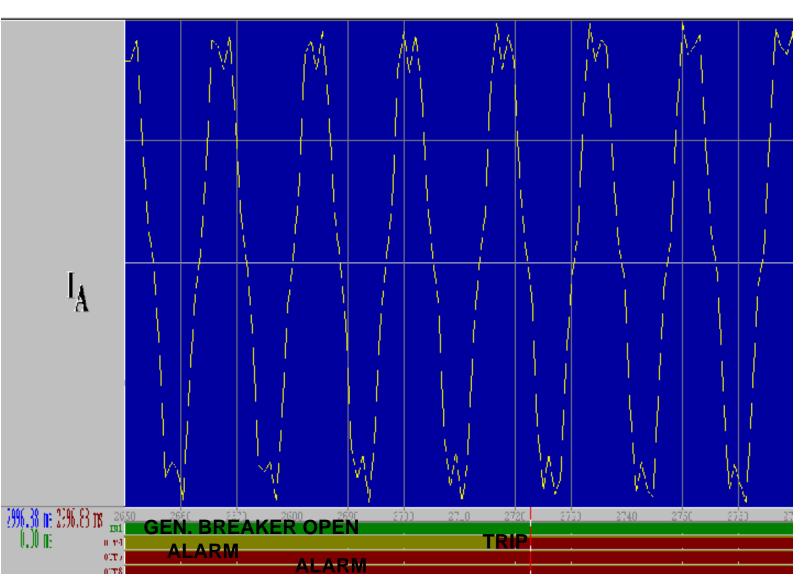








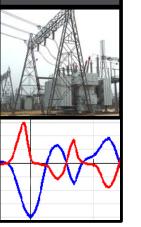




I<sub>A</sub>







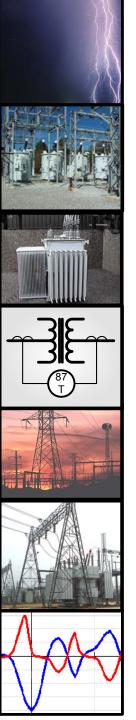
# DIGITAL RELAY TRANSFORMER PROTECTION

# **Digital Transformer Relays**





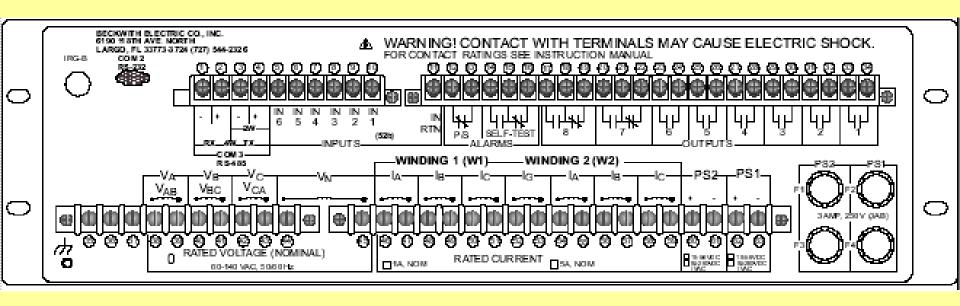




# **Digital Relay Features**

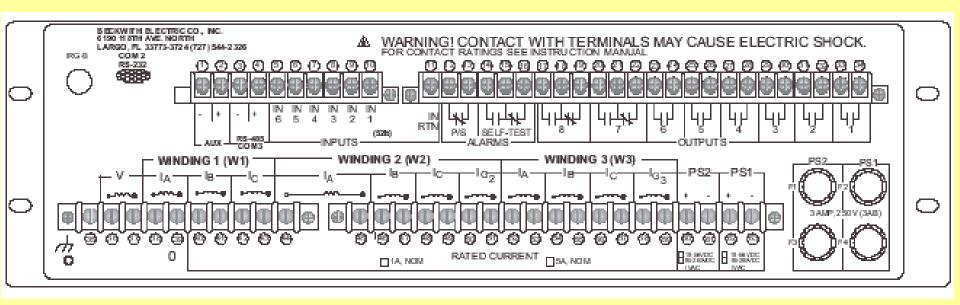
- + Self-Monitoring and Diagnostics.
- + Some Monitoring of VT and CT Inputs.
- + Multiple Input and Output Contacts
- + Multiple Setting Groups
- + Programmable Logic
- + Metering of all Inputs
- + Oscillography and Event Recording
- + Communications

# Two Winding Transformer Relay-- External Connections

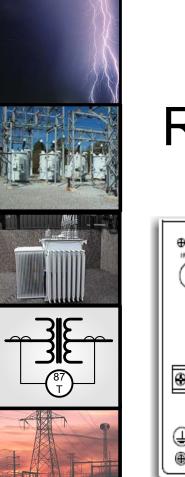


- •2 Three Phase Current, plus 1 Ground Current Input
- •3 Phase and One Ground Voltage Input

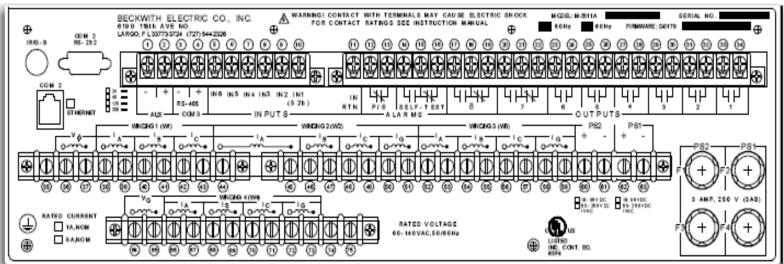
# Three Winding Transformer Relay-- External Connections



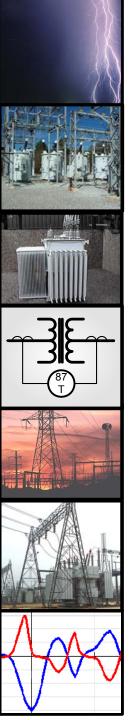
- •3 Three Phase Current, plus Two Ground Current Inputs!
- •One Voltage Input

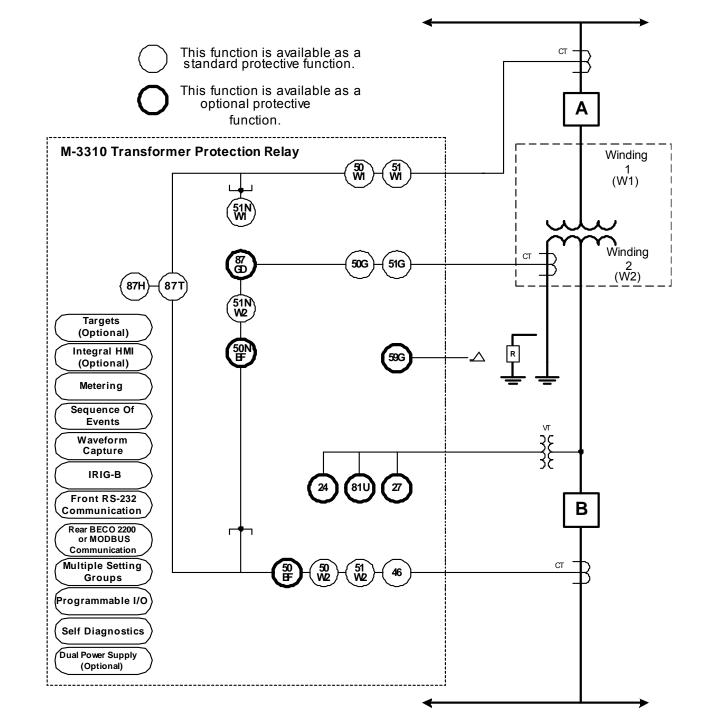


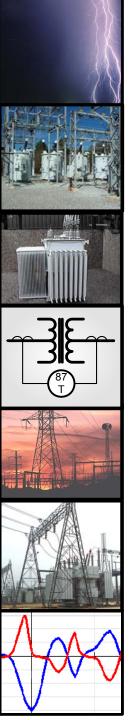
# Four Winding Transformer Relay-- External Connections

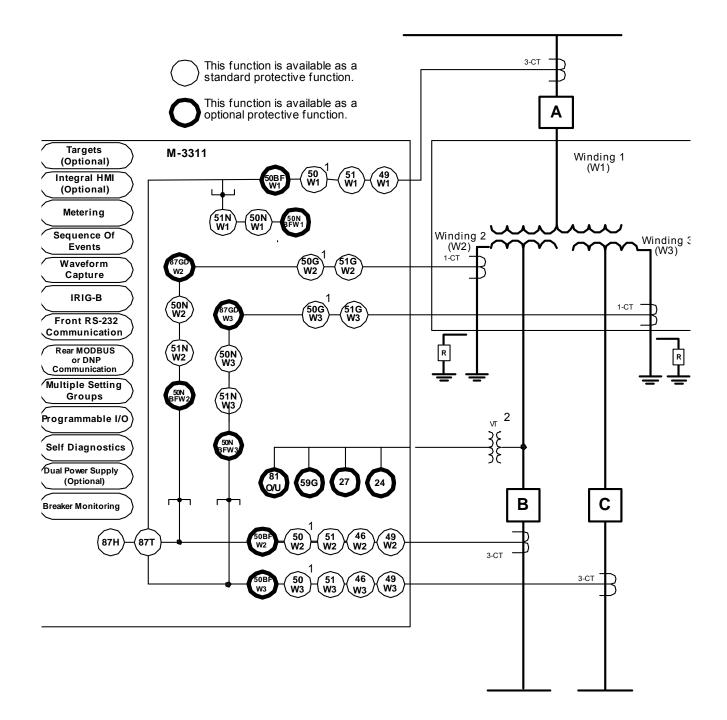


- •4 Three Phase Current, plus 3 Ground Current Inputs!
- Two Voltage Input

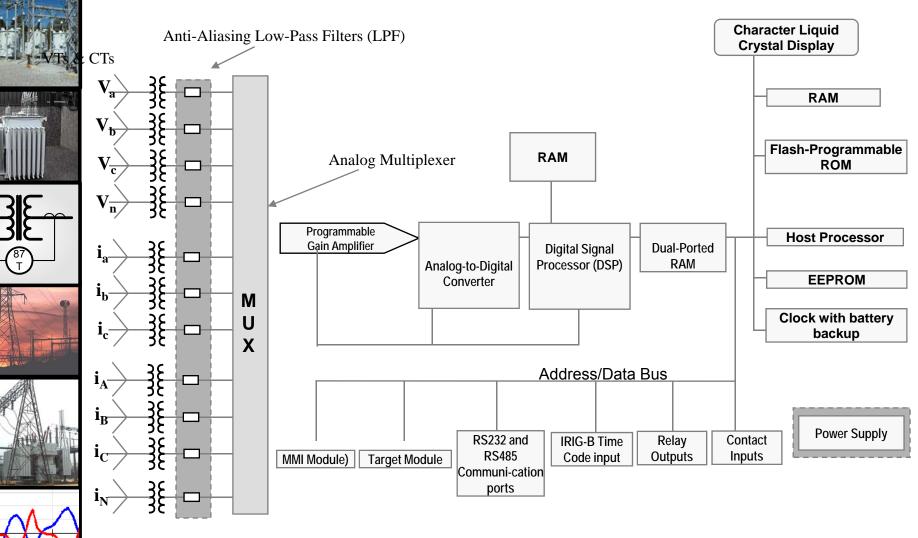


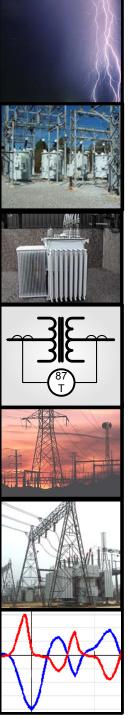






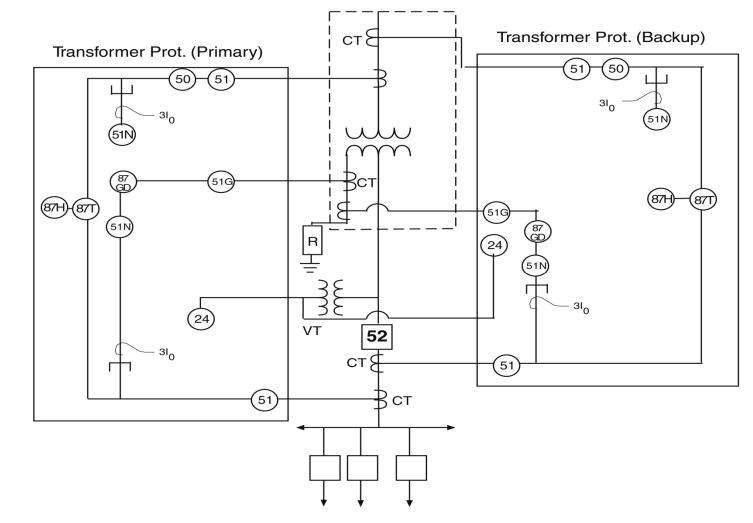
### Hardware Block Diagram



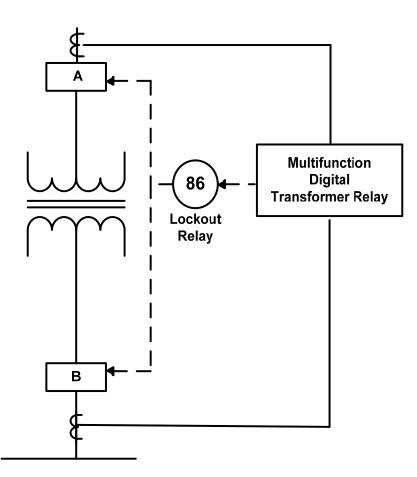


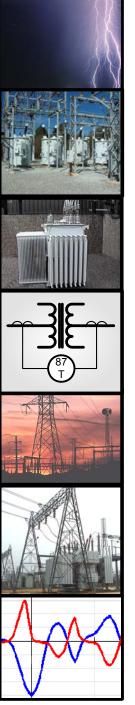
### **Transformer Protection**

### **TYPICAL PROTECTION WITH DUAL DIGITAL RELAYS**

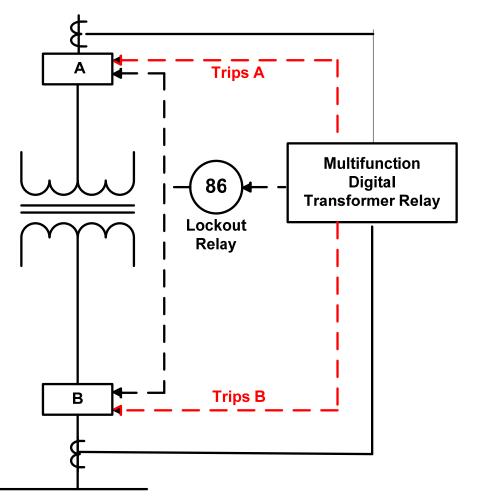


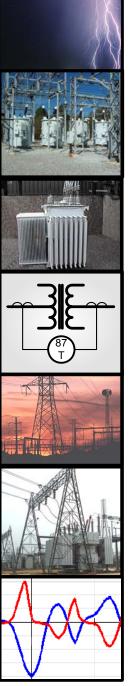
### Traditional Approach Tripping Redundancy

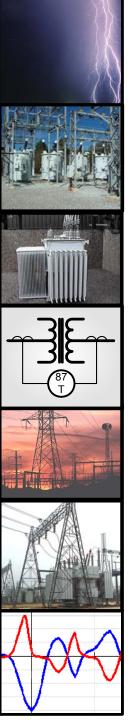




### New Approach Tripping Redundancy Improvement

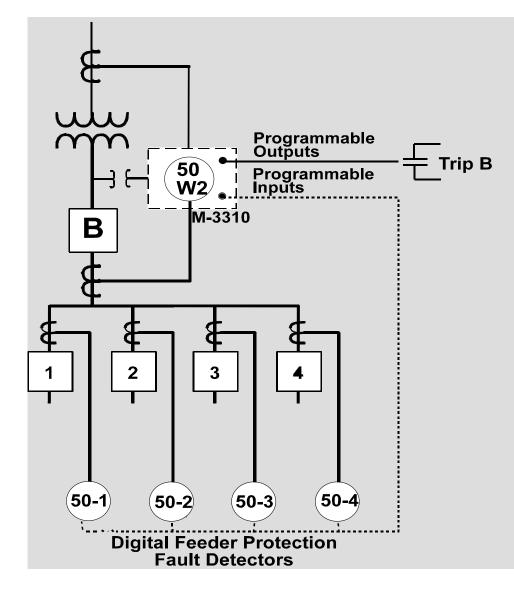




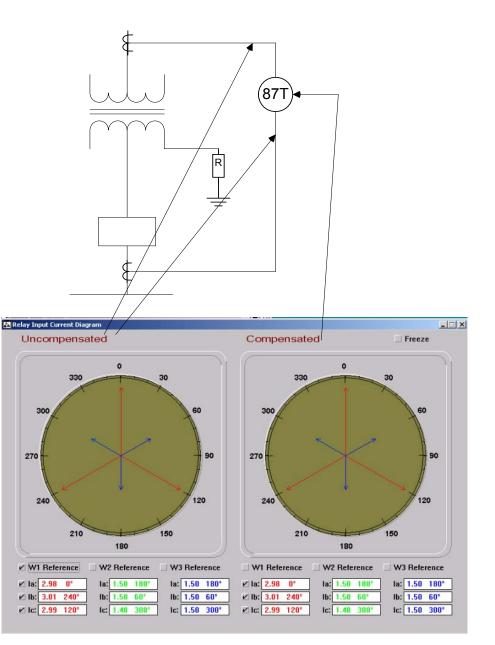


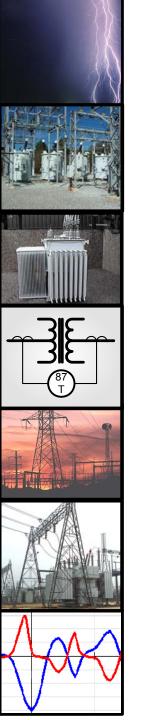
### **Schemes - Bus Fault Protection**

- Use interlocked overcurrent to avoid long time delays
  - Inexpensive solution for lower voltage distribution buses



### Vector Display, 87





### Waveform Capture

